FLEET CONTROL CENTER



The Fleet Control Center (CCF) is an specific software, designed and created by SENA GPS, for maintaining communications between a fleet of mobiles equipped with different communication means and systems and a Fleet Management (CGF) charge of Center in manipulating the data of the vehicle fleet.

A Fleet Control Centre has the following features:

Transparent management of different communication systems (GSM, TRUNKING, ORBCOMM, PMR), by using dedicated Communications Servers, installed to serve the communications ports.

6 Simultaneous control of up to 15 communication ports, with the different types same or of Communications Servers (e.q.: 2 GSM Servers and 3 Trunking Servers).

It communicates with management applications over a

TCP/IP network by means of sockets and with an self-descriptive frame protocol. Communication can also be maintained using an Active X control embedded in the actual application. This enables the use of an architecture distributed among different machines.

6 Ability to maintain multiple connections with different applications. It receive can commands from different applications time it and, every receives information from a vehicle in the fleet, it passes it on to all the applications currently connected to it.

It allows for the definition of different sub-fleets with access being restricted through the user / password identification.

Possibility to make reverse differential GPS corrections. All these combined features allow for a higher precision in the position of the vehicles, without the need for transmitting the correction parameters.

SERVERS

Various devices such as GSM, Trunking, PMR, Orbcomm and others are controlled by an unified specification for communications management.

SENA GPS has a set of drivers for the most common devices, while offering the client the possibility of implementing new means of communication.

In applications with a high traffic of messages, the CCF allows for the creation of as many simultaneous data servers as the client may wish, whether with one communications operator or with several ones.

DATA SUPPLY

The CCF supplies data to user applications by means of "Berkeley sockets" so that clients can work on operating systems as varied as BSD Unix, Solaris or WIN32.

Furthermore it allows connecting to as many user applications as are required, with a configurable privilege management system of operations on the fleet.

PROTOCOL

A development kit, with sample applications supplied with their source code, is available to enable the users to develop their own applications.

The data protocol between the CCF and other applications is self-descriptive. This means that, if the data supplied by the CCF is not implemented in the CGF, the latter may disregard them, without hindering the performance of the application in any way.

Since the CCF controls different communications devices, it can act as a transparent means of transmission for the user application data.

SERVER INFORMATION

Communications Port Status Server ID Server Name Server Instance Communications Port Server Means of Communication Server Id Error



CONFIGURATION DATA

Date and Time **Destination Telephone Destination User Data** Originating Telephone Originating User Data Error **Destination Telephone Error** Destination User Data Error Synchronisation Request **Destination String Destination String Error** Privilege Mapping Error CCF With fleet control CCF Properties List Vehicle Properties List Server Properties List Generated Frames Set Frame Progress Notification Use of Differential Corrections

VEHICLE DATA

Vehicle Identifier and Name Mobile Telephone Number Means of Communication with the Vehicle Position, speed and course data **GPS** Time Satellites in View and Navigator Mode Analog and digital signals Auto-response Time Auto-response Duration Activity Time Sleep Time Pool Response Type identifier, Telephone and Centre Means 1 to 6 Errors Reason for Submission PDOP Navigator Status Software Version Data Submission Mode Transmission Bits Server Id Number of Saved Records Time Between Saves Saving Configuration Record Size No. of Free Records No. of Downloaded Records Movement Sensor Save Order Message Code Message Date and Time of Last Message

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